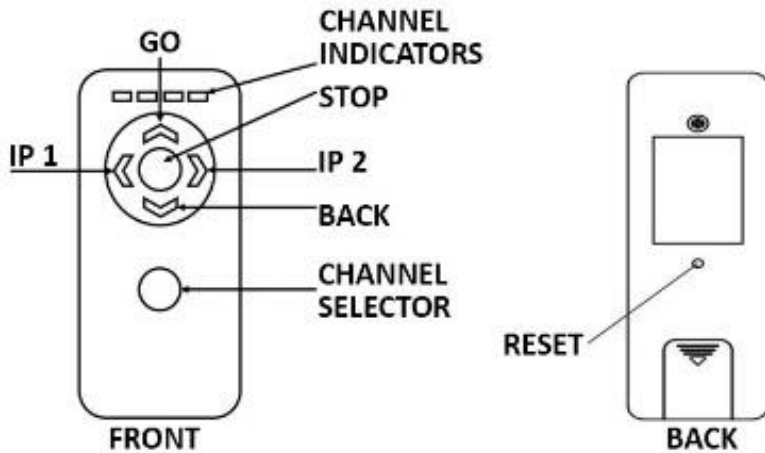


# Super Target Systems | Motor Quick Start Guide

Note: Check our website for the latest version of this manual.



Before using the remote control functions, user must pair the remote to the motor.

## Pairing process

<p>1. Press the motor <b>[RESET]</b> button for 3 seconds till the light on.</p>	<p>2. If the remote has multiple channels select the desired one by pressing the <b>[CHANNEL SELECTOR]</b> button.</p>	<p>3. Press the <b>[RESET]</b> button on the back of transmitter till the indicator light of the motor flash.</p>	<p>4. Press the motor <b>[RESET]</b> button again to confirm the operation.</p>

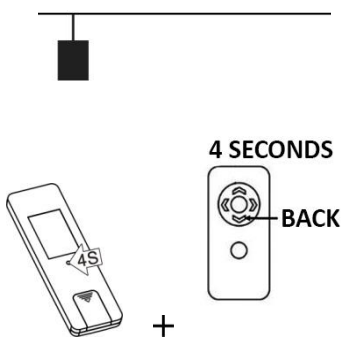
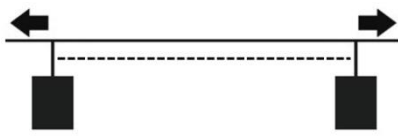
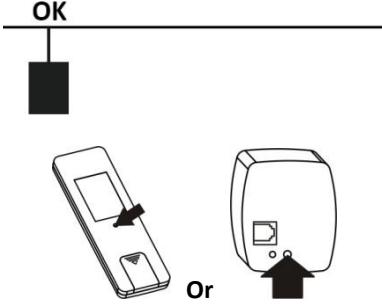
**Attention: Motor will start if powered and the target carrier bar is moved by hand.**

Motor will make relevant actions when you press **[GO]**, **[BACK]**, **[STOP]** button on transmitter or wall mounted controller.

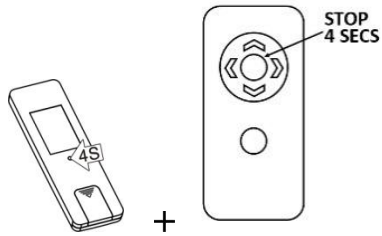
## Set Limit Range 1

<p>1. Press the <b>[RESET]</b> on the back of transmitter + <b>[GO]</b> button for 4 seconds. The motor shaft will rotate back and forth shortly to indicate that it is in adjusting mode for <b>Limit 1</b>.</p>	<p>2. Move the target holder into the suitable place for <b>Limit 1</b>.</p>	<p>3. Press <b>[RESET]</b> on the motor, the motor will quiver for a moment and the process will be finished.</p>


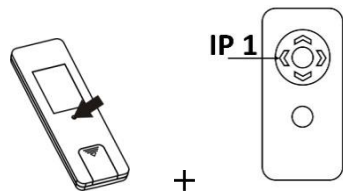
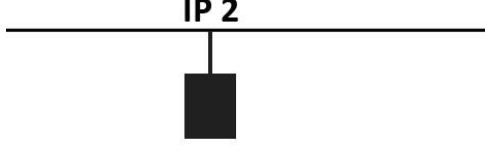
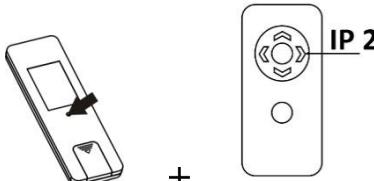
### Set Limit Range 2

		
<p>1. Press the <b>[RESET]</b> on the back of transmitter + <b>[BACK]</b> button for 4 seconds. The motor shaft will rotate back and forth shortly to indicate that it is in adjusting mode for <b>Limit 2</b>.</p>	<p>2. Move the target holder into the suitable place for <b>Limit 2</b>.</p>	<p>3. Press <b>[RESET]</b> on the motor, the motor will quiver for a moment and the process will be finished.</p>


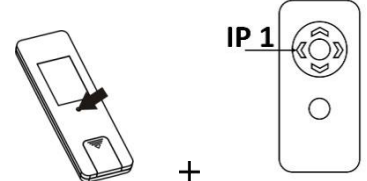
### Resetting the range limits

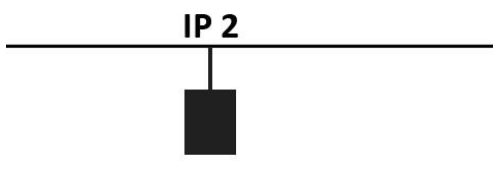
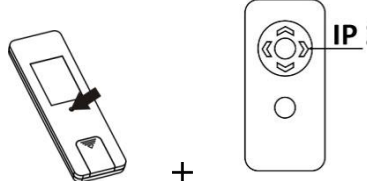

<p>1. Press the remote <b>[RESET]</b> + <b>[STOP]</b> button for 4 seconds.</p>

### Set intermediate stop function

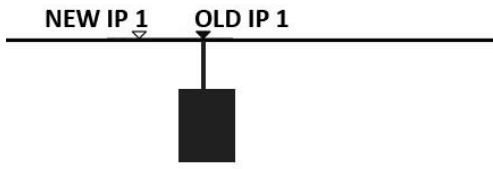
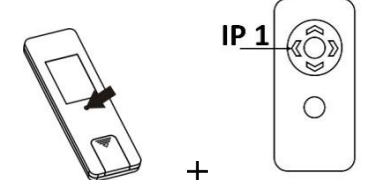
	
<p>1. Move and stop the Target Holder in desired place <b>IP1</b>.</p>	<p>2. Press <b>[RESET]</b>+<b>[IP1]</b> to set <b>IP1</b>.</p>
	
<p>1. Move and stop the Target Holder in desired place <b>IP2</b>.</p>	<p>2. Press <b>[RESET]</b>+<b>[IP2]</b> to set <b>IP2</b>.</p>


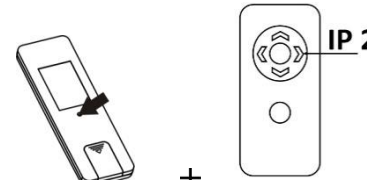
**Cancel intermediate stop point**

	
<p>1. Press <b>[IP1]</b>. Target Holder will move to <b>IP1</b>.</p>	<p>2. Press <b>[RESET]+[IP1]</b> button to cancel the stop point <b>IP1</b>.</p>

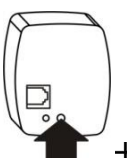
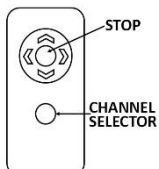

	
<p>1. Press <b>[IP2]</b>. Target Holder will move to <b>IP2</b>.</p>	<p>2. Press <b>[RESET]+[IP2]</b> button to cancel the stop point <b>IP2</b>.</p>

**Change the intermediate stop point**

	
<p>1. Move the target holder in new position <b>IP1</b>.</p>	<p>2. Press <b>[RESET]+[IP1]</b> to set new position of <b>IP1</b>.</p>

	
<p>1. Move the target holder in new position <b>IP2</b>.</p>	<p>2. Press <b>[RESET]+[IP2]</b> to set new position of <b>IP2</b>.</p>

**Change Motor direction**

		
<p>1. Press and Hold for 3s the motor <b>[RESET]</b> button.</p>	<p>2. Press at the same time the <b>[STOP]</b> and <b>[CHANNEL SELECTOR]</b> buttons.</p>	<p>3. Press <b>[RESET]</b> button on the motor.</p>