

Before using the remote control functions, user must pair the remote to the motor.

**Pairing process**

<p>1. Press the motor <b>[RESET]</b> button for 3 seconds till the light on.</p>	<p>2. If the remote has multiple channels select the desired one by pressing the <b>[CHANNEL SELECTOR]</b> button.</p>	<p>3. Press the <b>[RESET]</b> button on the back of transmitter till the indicator light of the motor flash.</p>	<p>4. Press the motor <b>[RESET]</b> button again to confirm the operation.</p>

Motor will make relevant actions when you press **[FORWARD]**, **[RETRIEVAL]**, **[STOP]** button on transmitter or switch. You can pull the Target Holder freely by hand when power failure occurs, but avoid sudden moves to reduce the risk of damaging the belt.

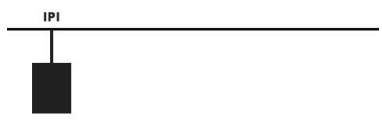
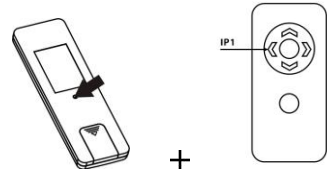

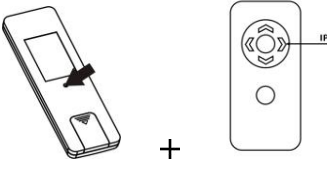
**Adjust the range limit**

<p>1. Press the <b>[RESET]</b> on the back of transmitter + <b>[RETRIEVAL]</b> button for 4 seconds. The motor shaft will rotate back and forth shortly to indicate that, it recorded the new limit.</p>	<p>2. Press the remote to adjust the limit slightly into the suitable place.</p>	<p>3. Press the <b>[RESET]</b> on remote or press the <b>[RESET]</b> on the motor, the motor will quiver for a moment and the process will be finished.</p>


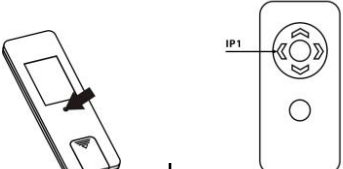
**Resetting the range limit**


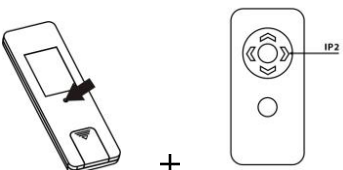
<p>1. Press the remote <b>[RESET]</b> + <b>[STOP]</b> button for 4 seconds.</p>

### Set intermediate stop function

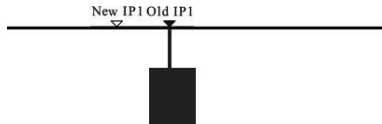
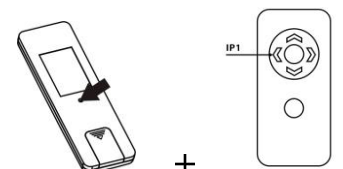
	
<p>1. Let the Target Holder stop at any place as <b>IP1</b> within the limit.</p>	<p>2. Press <b>[RESET]+[IP1]</b> to set <b>IP1</b>.</p>
	
<p>1. Let the Target Holder stop at any place as <b>IP2</b> within the limit.</p>	<p>2. Press <b>[RESET]+[IP2]</b> to set <b>IP2</b>.</p>


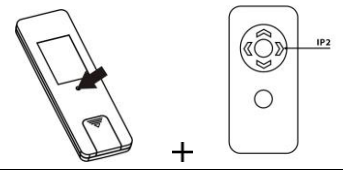
### Cancel intermediate stop point

	
<p>1. Press <b>[IP1]</b>. Target Holder will move to <b>IP1</b> automatically.</p>	<p>2. Press <b>[RESET]+[IP1]</b> button to cancel the stop point <b>IP1</b>.</p>

	
<p>1. Press <b>[IP2]</b>. Target Holder will move to <b>IP2</b> automatically.</p>	<p>2. Press <b>[RESET]+[IP2]</b> button to cancel the stop point <b>IP2</b>.</p>

### Change the intermediate stop point

	
<p>1. Let the Target Holder move to the new position of <b>IP1</b>.</p>	<p>2. Press <b>[RESET]+[IP1]</b> to set new position of <b>IP1</b>.</p>

	
<p>1. Let the Target Holder move to new position of <b>IP2</b>.</p>	<p>2. Press <b>[RESET]+[IP2]</b> to set new position of <b>IP2</b>.</p>